MUHAMMAD RAFEY TAHIR

♥Islamabad, Pakistan \$+92-3136052153 rafeyt21@gmail.com \$\$ RafeyTahir

EDUCATION

National University o <i>Master in Electrical E</i>	f Sciences & Technology, Islamabad (PK). ngineering (Control Systems) GPA: 3.70	Aug 2021 - Jan 2024
Core Courses: Optime tronics.	al Control, Convex Optimization, Nonlinear Control Systems, Adap	otive Control & Power Elec-
Muhammad Nawaz S Bachelor of Science in • Award-winning Final • Ranked in the top 10 • Registered Engineer	 Sharif University of Engineering & Technology, Multan (PK). Electrical Engineering, GPA: 3.61 (4th Position) Year Project. % of Engineering Science students. PEC: ELECT/94875 Control Systems Disited Levis Design Missesson Systems 	Oct 2017 - July 2021
Digital Signal Process	ing.	, industrial Control System,
Govt. Postgraduate (Intermediate (Pre-Eng	College, Khanewal (PK). ineering), Grade: A	April 2014 - Sept 2017
TECHNICAL SKILLS		
Professional: Programming: Software & Tools:	Communication Skills, Problem Solving, Data Management, Le Julia, Python, C/C++, Assembly Language, Ladder Logic Lang MATLAB/Simulink, Git, ROS, Proteous, Multisim, LabVIEW,	eadership uage(PLC), LATEX Microwind, Arduino IDE
WORK & RESEARCH	EXPERIENCE	
Research Assistant -I • Development of 6+ I • Implementation of Etation in industrial auto • Design and implement robotic precision and etation	Juman Centered Robotics Lab OOF robot manipulator, focusing on design, control, and integration herCAT communication protocols for high-DOF robotic manipulate mation systems. Itation of inverse kinematics algorithms for trajectory optimization a fficiency in dynamic environments.	Dec 2024 - Present a for automation tasks. ors, enabling seamless oper- and path planning, enhancing
 Product Excellence C Worked with Softwa health, and manage m ciency. 	officer - SkyElectric Pvt. Ltd re/Cloud team to develop an AI-based monitoring system to optim aintenance proactively. Analyzing solar and battery data to optim	<i>March</i> 2024 - <i>Dec</i> 2024 ize solar performance, track nize output and storage effi-
Managed alerts and s Control Systems Lab Research Assistant - A	ervice tickets, providing energy insights and timely customer suppo oratory -SEECS, NUST dvisor: Dr. Usman Ali	ort. Jun 2023 - Feb 2024
• Implementation of N hardware setup.	lodel-free Robust Adaptive controller on Quanser QNET Rotary In	nverted Pendulum Board 2.0
• Performance validati Graduate Research (Graduate Student Rese	on on Quanser QNET Vertical Take-off and Landing system 2.0 has Complex – SEECS, NUST <i>Parcher - Advisor: Dr. Usman Ali</i>	rdware setup. Sep 2022 - Jun 2023
 Conducting research Designing and imple Collaborating with a Assembling of a 6 De Circuit Design Autor 	on controller design and optimization techniques for underactuated mentation of a novel model-free control framework for underactuat research team to refine the approach and develop solutions to resea egree-of-Freedom Robot Manipulator from the Ground Up. nation using Reinforcement Learning.	l mechanical systems. red systems rch problems.
Digital Control Labo	ratory - DoEE, MNS-UET	April 2020 - Jun 2021

Research Associate - Advisor: Engr. Hamza Khan

• Conducting research on the designing of smart bionic prosthetic leg for limb amputee patients.

• Developed a smart safe embedded system that controls the leg using different modes for different activities.

Underactuated systems are those in which the number of actuators is less than the number of degrees of freedom. This makes them more challenging to control, but they are also more common in practice. Model-free control techniques are attractive because they does not require any information about system's dynamics. In my research, I have developed a new control framework using model-free robust adaptive controller for underactuated systems.

In recent years, there has been growing interest in the development of controller design and algorithms for underactuated systems.

Smart Bionic Prosthetic Leg (Best Final Year Project Award)

My Final Year Project is a Smart Prosthetic Leg which mainly focuses on patients of an above-the- knee amputee. In this project, we have designed a smart and safe embedded system that controls the leg using different modes for different activities. Due to the low cost of our design, this prosthetic technology could be applied in public sector hospitals to serve the less fortunate.

Semester Projects:

PROJECTS

- Air flow ball levitation using PID Controller · DC to AC Inverter
- Arduino Based Metal Detector
- Arduino Based Heart Rate Monitor

TEACHING EXPERIENCE

National University of Sciences & Technology	Islamabad, PK
 Teaching Assistant, MATH-816: Applied Linear Algebra 	Fall 2023
Muhammad Nawaz Sharif University of Engineering & Technology	Multan, PK
 Teaching Assistant, CSC-341: Introduction to Computing 	Fall 2019
• Teaching Assistant, EEE-562: Linear Control Systems	Fall 2020

COURSES & CERTIFICATIONS

Mathematics for Engineers	-The Hong Kong University of Science and Technology
Introduction to Programming with MATLAB	-Vanderbilt University
Machine Learning with Python	-IBM
Modern Robotics: Mechanics, Planning and Control	-Northwestern University

SCHOLARSHIPS & AWARDS

- · Honored with a laptop by the Prime Minister of Pakistan for sustaining a high GPA in Masters.
- Dean's Honour Roll Fall 2019, Spring 2020, Fall 2020, Spring 2021
- HEC Merit based Scholarship

DC-DC Buck Boost Converter

- · Awarded Scholarship AMERICA from PepsiCo Foundation in B.Sc. Electrical Engineering.
- Best Final Year Project of Batch EE-2017.

LANGUAGES

• English (IELTS : 6.5)

REFERENCES

Dr. Usman Ali

Assistant Professor School of Electrical Engineering and Computer Sciences National University of Sciences & Technology Email: usman.ali@seecs.edu.pk

Muhammad Ali Murtaza, Ph.D.

Electrical and Computer Engineering Department Georgia Institute of Technology, Atlanta, USA Email: mamurtaza@gatech.edu

Dr. Rameez Hayat

Assistant Professor School of Electrical Engineering and Computer Sciences National University of Sciences & Technology Email: rameez.hayat@seecs.edu.pk

Model-Free Intelligent Control Design For Underactuated Mechanical Systems

-Bachelor's Thesis

• Urdu